

Notice of References Cited

Application/Control No.

10/551,039

Applicant(s)/Patent Under
Reexamination
FUJITA ET AL.

Examiner

NIKHIL SRIRAMAN

Art Unit

3664

Page 1 of 1

U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
*	A	US-6,266,577 B1	07-2001	Popp et al.	700/248
*	B	US-2003/0060930 A1	03-2003	Fujita et al.	700/245
*	C	US-6,560,511 B1	05-2003	Yokoo et al.	700/245
*	D	US-2003/0171846 A1	09-2003	Murray et al.	700/245
*	E	US-2004/0002790 A1	01-2004	Senn, Paul	700/246
*	F	US-2004/0030451 A1	02-2004	Solomon, Neal	700/245
*	G	US-2004/0236467 A1	11-2004	Sano, Shigeo	700/245
*	H	US-6,889,117 B2	05-2005	Sabe et al.	700/245
*	I	US-7,082,351 B2	07-2006	Hara et al.	700/248
*	J	US-7,117,067 B2	10-2006	McLurkin et al.	700/245
	K	US-			
	L	US-			
	M	US-			

FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	O					
	P					
	Q					
	R					
	S					
	T					

NON-PATENT DOCUMENTS

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)			
	U	Rybski, Performance of a Distributed Robotic System Using Shared Communications Channels, October 2002, IEEE, Volume 18, pages 713-727.			
	V	Ye, Evaluating Control Strategies for Wireless-Network Robots Using an Integrated Robot and Network Simulation, May 2001, IEEE, International Conference on Robotics & Automation, p2941-2947.			
	W	Piaggio, A Programmable Environment for Real-Time Control of Distributed Multiple Robotic Systems, Advanced Robotics, Vol. 14, 2000, p75-86.			
	X	Mutambara, Estimation and Control for a Modular Wheeled Mobile Robot, IEEE Transactions on Control Systems Technology, Vol. 8, No. 1, January 2000.			

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a))
 Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.